

## Lecture 7.

### Self-Concordant Barriers

- Motivation.
- Definition of Self-Concordant Barriers.
- Main Properties.
- Standard Minimization Problem.
- Central Path.
- Path-Following Method.
- How to initialize the process?
- Problems with functional constraints.

## Motivation

What we have now:

- An open convex set  $\text{dom } f$ , which contains no straight line.
- A self-concordant function  $f$ . This means that  $f \in C^3(\text{dom } f)$ , it is closed and convex and

$$D^3 f(x)[h, h, h] \leq 2 \|h\|_x^3,$$

for all  $x \in \text{dom } f$  and  $h \in R^n$ .

(For this function  $M_f = 2$ ; we call such functions the *standard* self-concordant functions).

- $f$  is a barrier for  $\text{dom } f$ .
- The Newton Method is very efficient in minimization  $f$  over  $\text{dom } f$ .

We want to use these objects in the scheme of *Sequential Unconstrained Minimization*.

## Standard Problem

Denote

$$\text{Dom } f = \text{cl}(\text{dom } f).$$

We call a constrained minimization problem *standard* if:

- it has the following form:

$$\min\{\langle c, x \rangle \mid x \in Q\}, \quad (7.1)$$

where  $Q$  is a closed convex set.

- We have a self-concordant function  $f$  such that

$$\text{Dom } f = Q.$$

### Central path

Define the parametric penalty function

$$f(t; x) = t\langle c, x \rangle + f(x)$$

with  $t \geq 0$ . Note that  $f(t; x)$  is self-concordant in  $x$  (see Corollary 6.1).

Denote

$$x^*(t) = \arg \min_{x \in \text{dom } f} f(t; x).$$

This trajectory is called *the central path* of the problem (7.1).

## Our goals:

- We can expect that  $x^*(t) \rightarrow x^*$  as  $t \rightarrow \infty$ .
- We want to follow the central path.

## Note:

- The Newton Method for function  $f(t; x)$  has a local quadratic convergence.
- We have an exact description of the region of quadratic convergence ( $\lambda_{f(t; \cdot)}(x) \leq \beta < \bar{\lambda}$ ).

Assume that we have computed  $x = x^*(t)$ .

We can increase  $t$ :

$$t_+ = t + \Delta, \quad \Delta > 0,$$

but we want to keep  $x$  in the region of quadratic convergence of the Newton Method for the function  $f(t + \Delta; \cdot)$ :

$$\lambda_{f(t+\Delta; \cdot)}(x) \leq \beta < \bar{\lambda}.$$

Note that the update  $t \rightarrow t_+$  does not change the Hessian:

$$f''(t + \Delta; x) = f''(t; x).$$

**Question:** How large can be  $\Delta$ ?

## Central path equation:

$$tc + f'(x^*(t)) = 0. \quad (7.2)$$

Since  $tc + f'(x) = 0$ , we have:

$$\begin{aligned} \lambda_{f(t+\Delta; \cdot)}(x) &= \| t_+c + f'(x) \|_x^* \\ &= \Delta \| c \|_x = \frac{\Delta}{t} \| f'(x) \|_x^* \leq \beta. \end{aligned}$$

## Conclusion:

If we want to increase  $t$  in a *linear rate*, we need to assume that the value

$$\| f'(x) \|_x^{*2} \equiv \langle [f''(x)]^{-1} f'(x), f'(x) \rangle$$

is *uniformly bounded* on  $\text{dom } f$ .

Thus, we come to the definition of *self-concordant barrier*.

## Definition of Self-Concordant Barriers

**Definition 7.1** Let  $F(x)$  be a standard self-concordant function. We call it a  $\nu$ -self-concordant barrier for the set  $\text{Dom } F$ , if

$$\max_{u \in R^n} [2\langle F'(x), u \rangle - \langle F''(x)u, u \rangle] \leq \nu \quad (7.3)$$

for all  $x \in \text{dom } F$ .

The value  $\nu$  is called the *parameter* of the barrier.

### Note:

1. We don't assume that  $F''(x)$  is non-degenerate.
2. If  $F''(x)$  is non-degenerate, then (7.3) is equivalent to the following:

$$\langle [F''(x)]^{-1}F'(x), F'(x) \rangle \leq \nu. \quad (7.4)$$

3. We have the following consequence of the inequality (7.3):  $\forall u \in R^n$

$$\langle F'(x), u \rangle^2 \leq \nu \langle F''(x)u, u \rangle, \quad (7.5)$$

(To see that for  $u$  with  $\langle F''(x)u, u \rangle > 0$ , replace  $u$  in (7.3) by  $\lambda u$  and find the maximum of LHS in  $\lambda$ .)

### **At this moment:**

- We are almost sure that we can follow the central path defined by a self-concordant barrier.
- We don't have any examples of these barriers.
- We don't know the properties of these barriers.
- We don't know for which convex sets such barriers exist.

That is our program.

Let us check our examples of self-concordant functions from Lecture 6.

1. Linear function

$$f(x) = \alpha + \langle a, x \rangle, \quad \text{dom } f = \mathbb{R}^n.$$

Clearly, it is not a self-concordant barrier since  $f''(x) = 0$ .

2. Convex quadratic function:

$$f(x) = \alpha + \langle a, x \rangle + \frac{1}{2} \langle Ax, x \rangle,$$

$$A = A^T > 0, \quad \text{dom } f = \mathbb{R}^n,$$

$$f'(x) = a + Ax, \quad f''(x) = A.$$

Then

$$\begin{aligned} \langle [f(x)]^{-1} f'(x), f'(x) \rangle &= \langle A^{-1}(Ax - a), Ax - a \rangle \\ &= \langle Ax, x \rangle - 2\langle a, x \rangle + \langle A^{-1}a, a \rangle. \end{aligned}$$

Clearly, this value is unbounded from above on  $\mathbb{R}^n$ .

3. Logarithmic barrier for a ray:

$$F(x) = -\ln x, \quad \text{dom } F = \{x \in \mathbb{R}^1 \mid x > 0\},$$

$$F'(x) = -\frac{1}{x}, \quad F''(x) = \frac{1}{x^2} > 0.$$

Therefore

$$\frac{(F'(x))^2}{F''(x)} = \frac{1}{x^2} \cdot x^2 = 1.$$

Thus,  $F(x)$  is a  $\nu$ -self-concordant barrier with  $\nu = 1$ .



4. Logarithmic barrier for a quadratic region.

Let  $A = A^T \geq 0$ . Consider the *concave* function

$$\phi(x) = \alpha + \langle a, x \rangle - \frac{1}{2} \langle Ax, x \rangle.$$

Define

$$F(x) = -\ln \phi(x), \quad \text{dom } f = \{x \in R^n \mid \phi(x) > 0\}.$$

Then

$$\begin{aligned} \langle F'(x), u \rangle &= -\frac{1}{\phi(x)} [\langle a, u \rangle - \langle Ax, u \rangle], \\ \langle F''(x)u, u \rangle &= \frac{1}{\phi^2(x)} [\langle a, u \rangle - \langle Ax, u \rangle]^2 \\ &\quad + \frac{1}{\phi(x)} \langle Au, u \rangle. \end{aligned}$$

Denote

$$\omega_1 = \langle F'(x), u \rangle, \quad \omega_2 = \frac{1}{\phi(x)} \langle Au, u \rangle.$$

Then

$$\langle F''(x)u, u \rangle = \omega_1^2 + \omega_2 \geq \omega_1^2.$$

Therefore

$$2\langle F'(x), u \rangle - \langle F''(x)u, u \rangle \leq 2\omega_1 - \omega_1^2 \leq 1.$$

Thus,  $F(x)$  is a  $\nu$ -self-concordant barrier with  $\nu = 1$ .

## Simple Properties

**Theorem 7.1** *Let  $F(x)$  be a self-concordant barrier.*

*Then the function*

$$\langle c, x \rangle + F(x)$$

*is self-concordant on  $\text{dom } F$ .*

**Proof:**

Since  $F(x)$  is a self-concordant function, we just refer to Corollary 6.1.  $\square$

**Note:**

This property is very important for path-following schemes.

**Theorem 7.2** *Let  $F_i$  are  $\nu_i$ -self-concordant barriers,  $i = 1, 2$ . Then*

$$F(x) = F_1(x) + F_2(x)$$

*is a self-concordant barrier for the set*

$$\text{Dom } F = \text{Dom } F_1 \cap \text{Dom } F_2$$

*with the parameter*

$$\nu = \nu_1 + \nu_2.$$

**Proof:**

Note that  $F$  is a standard self-concordant function in view of Theorem 6.1.

Let us fix  $x \in \text{dom } F$ . Then

$$\begin{aligned} & \max_{u \in R^n} [ 2\langle F'(x)u, u \rangle - \langle F''(x)u, u \rangle ] \\ &= \max_{u \in R^n} [ 2\langle F_1'(x)u, u \rangle - \langle F_1''(x)u, u \rangle \\ & \quad + 2\langle F_2'(x)u, u \rangle - \langle F_2''(x)u, u \rangle ] \\ &\leq \max_{u \in R^n} [ 2\langle F_1'(x)u, u \rangle - \langle F_1''(x)u, u \rangle ] \\ &+ \max_{u \in R^n} [ 2\langle F_2'(x)u, u \rangle - \langle F_2''(x)u, u \rangle ] \leq \nu_1 + \nu_2. \end{aligned}$$

□

**Theorem 7.3** *Let  $\mathcal{A}(x) = Ax + b$  be a linear operator:*

$$\mathcal{A}(x) : R^n \rightarrow R^m.$$

*Assume that the function  $F(y)$  is a  $\nu$ -self-concordant barrier.*

*Then  $\Phi(x) = F(\mathcal{A}(x))$  is a  $\nu$ -self-concordant barrier for the set*

$$\text{Dom } \Phi = \{x \in R^n \mid \mathcal{A}(x) \in \text{Dom } F\}.$$

**Proof:**

The function  $\Phi(x)$  is a standard self-concordant function in view of Theorem 10.2.

Let us fix  $x \in \text{dom } \Phi$ . Then  $y = \mathcal{A}(x) \in \text{dom } F$ .

Note that for any  $u \in R^n$  we have:

$$\begin{aligned} \langle \Phi'(x), u \rangle &= \langle F'(y), Au \rangle, \\ \langle \Phi''(x)u, u \rangle &= \langle F''(y)Au, Au \rangle. \end{aligned}$$

Therefore

$$\begin{aligned} &\max_{u \in R^n} [2\langle \Phi'(x), u \rangle - \langle \Phi''(x)u, u \rangle] \\ &= \max_{u \in R^n} [2\langle F'(y), Au \rangle - \langle F''(y)Au, Au \rangle] \\ &\leq \max_{v \in R^m} [2\langle F'(y), v \rangle - \langle F''(y)v, v \rangle] \leq \nu. \end{aligned}$$

□

## Main Inequalities

**Theorem 7.4** *Let  $F(x)$  be a  $\nu$ -self-concordant barrier.*

*Then for any  $x \in \text{dom } F$  and  $y \in \text{Dom } F$  we have:*

$$\langle F'(x), y - x \rangle \leq \nu. \quad (7.6)$$

**Proof:**

Let  $x \in \text{dom } F$  and  $y \in \text{Dom } F$ . Consider the function

$$\phi(t) = \langle F'(x + t(y - x)), y - x \rangle, \quad t \in [0, 1].$$

If  $\phi(0) \leq 0$ , then (7.6) is trivial.

Suppose that  $\phi(0) > 0$ . Note that in view of (7.5) we have:

$$\begin{aligned} \phi'(t) &= \langle F''(x + t(y - x))(y - x), y - x \rangle \\ &\geq \frac{1}{\nu} \langle F'(x + t(y - x)), y - x \rangle^2 = \frac{1}{\nu} \phi^2(t). \end{aligned}$$

Therefore  $\phi(t)$  increases and it is positive for  $t \in [0, 1)$ . Moreover,

$$-\frac{1}{\phi(t)} + \frac{1}{\phi(0)} \geq \frac{1}{\nu} t, \quad t \in [0, 1).$$

This means that

$$\langle F'(x), y - x \rangle = \phi(0) \leq \frac{\nu}{t}$$

for all  $t \in [0, 1)$ . □

**Theorem 7.5** *Let  $F(x)$  be a  $\nu$ -self-concordant barrier.*

*Then for any  $x \in \text{dom } F$  and  $y \in \text{Dom } F$  such that*

$$\langle F'(x), y - x \rangle \geq 0 \quad (7.7)$$

*we have:*

$$\|y - x\|_x \leq \nu + 2\sqrt{\nu}. \quad (7.8)$$

**Proof:**

Denote  $r = \|y - x\|_x$ . Let  $r > \sqrt{\nu}$ . Consider

$$y_\alpha = x + \alpha(y - x), \quad \alpha = \frac{\sqrt{\nu}}{r} < 1.$$

In view of our assumption (7.7) and Theorem 10.7 we have:

$$\begin{aligned} \omega &\equiv \langle F'(y_\alpha), y - x \rangle \geq \langle F'(y_\alpha) - F'(x), y - x \rangle \\ &= \frac{1}{\alpha} \langle F'(y_\alpha) - F'(x), y_\alpha - x \rangle \\ &\geq \frac{1}{\alpha} \cdot \frac{\|y_\alpha - x\|_x^2}{1 + \|y_\alpha - x\|_x^2} = \frac{\alpha \|y - x\|_x^2}{1 + \alpha \|y - x\|_x} = \frac{r\sqrt{\nu}}{1 + \sqrt{\nu}}. \end{aligned}$$

On the other hand, in view of (7.6), we obtain:

$$(1 - \alpha)\omega = \langle F'(y_\alpha), y - y_\alpha \rangle \leq \nu.$$

Thus,

$$\left(1 - \frac{\sqrt{\nu}}{r}\right) \frac{r\sqrt{\nu}}{1 + \sqrt{\nu}} \leq \nu,$$

and that is exactly (7.8). □

## Analytic Center

Let  $F(x)$  be a  $\nu$ -self-concordant barrier for the set  $\text{Dom } F$ . The point

$$x_F^* = \arg \min_{x \in \text{dom } F} F(x),$$

(if exists), is called the *analytic center* of the convex set  $\text{Dom } F$ , generated by the barrier  $F(x)$ .

**Theorem 7.6** *Assume that the analytic center of a  $\nu$ -self-concordant barrier  $F(x)$  exists.*

*Then for any  $x \in \text{Dom } F$  we have:*

$$\|x - x_F^*\|_{x_F^*} \leq \nu + 2\sqrt{\nu}.$$

*Moreover, for any  $x \in R^n$  such that*

$$\|x - x_F^*\|_{x_F^*} \leq 1$$

*we have  $x \in \text{Dom } F$ .*

**Proof:**

The first statement follows from Theorem 7.5 since  $F'(x_F^*) = 0$ .

The second statement follows from Theorem 6.5. □

Thus, the *asphericity* of the set  $\text{Dom } F$  in the metric  $\|\cdot\|_{x_F^*}$  with respect to  $x_F^*$  is

$$\nu + 2\sqrt{\nu}.$$

## Remarks:

1. If  $\text{Dom } F$  contains no straight line, the existence of  $x_F^*$  implies the boundedness of  $\text{Dom } F$ .

(Since then  $F''(x_F^*)$  is nondegenerate, see Theorem 6.3.)

2. For a general convex set in  $R^n$  the asphericity does not exceed  $n$  (John Theorem).

3. We obtained a bound for the asphericity in terms of *parameter* of the barrier.

This value does not depend on the dimension.



**Corollary 7.1** *Let  $\text{Dom } F$  be bounded.*

*Then for any  $x \in \text{dom } F$  and  $v \in R^n$  we have:*

$$\|v\|_x^* \leq (\nu + 2\sqrt{\nu}) \|v\|_{x_F^*}^* .$$

**Proof:**

Let us show that

$$\begin{aligned} \|v\|_x^* &\equiv \langle [F''(x)]^{-1}v, v \rangle^{1/2} \\ &= \max\{\langle v, u \rangle \mid \langle F''(x)u, u \rangle \leq 1\}. \end{aligned}$$

Indeed, in view of Theorem 4.17, the solution of this problem  $u^*$  satisfies the condition:

$$v = \lambda^* F''(x)u^*, \quad \langle F''(x)u^*, u^* \rangle = 1.$$

Therefore  $\langle v, u^* \rangle = \langle [F''(x)]^{-1}v, v \rangle^{1/2}$ .

Further, in view of Theorem 6.5 and Theorem 7.6,

$$\begin{aligned} B &\equiv \{y \in R^n \mid \|y - x\|_x \leq 1\} \subseteq \text{Dom } F \\ &\subseteq \{y \in R^n \mid \|y - x_F^*\|_x \leq \nu + 2\sqrt{\nu}\} \equiv B_*. \end{aligned}$$

Therefore, using again Theorem 7.6, we have:

$$\begin{aligned} \|v\|_x^* &= \max\{\langle v, y - x \rangle \mid y \in B\} \\ &\leq \max\{\langle v, y - x \rangle \mid y \in B_*\} \\ &= \langle v, x_F^* - x \rangle + (\nu + 2\sqrt{\nu}) \|v\|_{x_F^*}^* . \end{aligned}$$

Note that  $\|v\|_x^* = \|-v\|_x^*$ . Therefore we can assume that  $\langle v, x_F^* - x \rangle \leq 0$ .  $\square$

## Path-following Scheme

**Standard Problem:** (Mediator)

$$\min\{\langle c, x \rangle \mid x \in Q\}, \quad (7.9)$$

where

- $Q \equiv \text{Dom } F$  is a *bounded* closed convex set with nonempty interior;
- $F$  is a  $\nu$ -self-concordant barrier.

We are going to solve (7.9) by following the *central path*:

$$x^*(t) = \arg \min_{x \in \text{dom } F} f(t; x), \quad (7.10)$$

where  $f(t; x) = t\langle c, x \rangle + F(x)$  and  $t \geq 0$ .

**Note:**

1. Any point of the central path satisfies the equation

$$tc + F'(x^*(t)) = 0. \quad (7.11)$$

2. Since  $Q$  is bounded,  $x_F^*$  exists and

$$x^*(0) = x_F^*. \quad (7.12)$$

We are going to update the points, satisfying the *approximate centering condition*:

$$\lambda_{f(t;\cdot)}(x) \equiv \| f'(t; x) \|_x^* = \| tc + F'(x) \|_x^* \leq \beta, \quad (7.13)$$

where  $\beta$  is small enough.

Let us show that this is a reasonable goal.

**Theorem 7.7** *For any  $t > 0$  we have*

$$\langle c, x^*(t) \rangle - c^* \leq \frac{\nu}{t}, \quad (7.14)$$

where  $c^*$  is the optimal value of (7.9).

If  $x$  satisfies (7.13), then

$$\langle c, x \rangle - c^* \leq \frac{1}{t} \left( \nu + \frac{(\beta + \sqrt{\nu})\beta}{1 - \beta} \right). \quad (7.15)$$

**Proof:**

Let  $x^*$  be a solution to (7.9). In view of (7.11) and (7.6) we have:

$$\langle c, x^*(t) - x^* \rangle = \frac{1}{t} \langle F'(x^*(t)), x^* - x^*(t) \rangle \leq \frac{\nu}{t}.$$

Further, let  $x$  satisfy (7.13). Denote  $\lambda = \lambda_{f(t;\cdot)}(x)$ . Then

$$\begin{aligned} t \langle c, x - x^*(t) \rangle &= \langle f'(t; x) - F'(x), x - x^*(t) \rangle \\ &\leq (\lambda + \sqrt{\nu}) \| x - x^*(t) \|_x \leq (\lambda + \sqrt{\nu}) \frac{\lambda}{1 - \lambda} \leq \frac{(\beta + \sqrt{\nu})\beta}{1 - \beta} \end{aligned}$$

in view of (7.4), Theorem 6.11 and (7.13).  $\square$

## One step of Path-following Scheme

Assume that  $x \in \text{dom } F$ .

Let us analyze the following iterate:

$$\left. \begin{aligned} t_+ &= t + \frac{\gamma}{\|c\|_x^*}, \\ x_+ &= x - [F''(x)]^{-1}(t_+c + F'(x)). \end{aligned} \right\} \quad (7.16)$$

**Theorem 7.8** *Let  $x$  satisfy (7.13):*

$$\|tc + F'(x)\|_x^* \leq \beta$$

*with  $\beta < \bar{\lambda} = \frac{3-\sqrt{5}}{2}$ . Then for  $\gamma$ , such that*

$$|\gamma| \leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}} - \beta, \quad (7.17)$$

*we have again  $\|t_+c + F'(x_+)\|_{x_+}^* \leq \beta$ .*

**Proof:**

Denote  $\lambda_0 = \|tc + F'(x)\|_x^* \leq \beta$ ,

$$\lambda_1 = \|t_+c + F'(x)\|_x^*, \quad \lambda_+ = \|t_+c + F'(x_+)\|_{x_+}^* .$$

Then  $\lambda_1 \leq \lambda_0 + |\gamma| \leq \beta + |\gamma|$  and

$$\lambda_+ \leq \left(\frac{\lambda_1}{1-\lambda_1}\right)^2 \equiv [\omega'_*(\lambda_1)]^2$$

in view of Theorem 6.12. It remains to note that (7.17) is equivalent to

$$\omega'_*(\beta + |\gamma|) \leq \sqrt{\beta},$$

(recall that  $\omega'(\omega'_*(\tau)) = \tau$ ). □

**Lemma 7.1** *Let  $x$  satisfy (7.13) then*

$$\|c\|_x^* \leq \frac{1}{t}(\beta + \sqrt{\nu}). \quad (7.18)$$

**Proof:**

Indeed, in view of (7.13) and (7.4), we have

$$\begin{aligned} t \|c\|_x^* &= \|f'(t; x) - F'(x)\|_x^* \\ &\leq \|f'(t; x)\|_x^* + \|F'(x)\|_x^* \leq \beta + \sqrt{\nu}. \end{aligned}$$

□

Let us fix the parameters:

$$\beta = \frac{1}{9}, \quad \gamma = \frac{\sqrt{\beta}}{1+\sqrt{\beta}} - \beta = \frac{5}{36}. \quad (7.19)$$

**Conclusion:**

1. We can follow the central path, using the rule (7.16).
2. The possible rate for *increasing*  $t$  is

$$t_+ \geq \left(1 + \frac{5}{4 + 36\sqrt{\nu}}\right) \cdot t.$$

3. The possible rate for *decreasing*  $t$  is

$$t_+ \geq \left(1 - \frac{5}{4 + 36\sqrt{\nu}}\right) \cdot t.$$

## Main Process (7.20)

0. Set  $t_0 = 0$ . Choose an accuracy  $\epsilon > 0$  and  $x_0 \in \text{dom } F$  such that

$$\| F'(x_0) \|_{x_0}^* \leq \beta.$$

1.  $k$ th iteration ( $k \geq 0$ ).

$$\text{Set } t_{k+1} = t_k + \frac{\gamma}{\|c\|_{x_k}^*},$$

$$x_{k+1} = x_k - [F''(x_k)]^{-1}(t_{k+1}c + F'(x_k)).$$

2. Stop the process if  $\nu + \frac{(\beta + \sqrt{\nu})\beta}{1 - \beta} \leq \epsilon t_k$ . □

**Theorem 7.9** *The scheme (7.20) terminates no more than after  $N$  steps,*

$$N \leq O\left(\sqrt{\nu} \ln \frac{\nu \|c\|_{x_F^*}^*}{\epsilon}\right).$$

Moreover,  $\langle c, x_N \rangle - c^* \leq \epsilon$ .

**Proof:**

Note that  $r_0 \equiv \|x_0 - x_F^*\|_{x_0} \leq \frac{\beta}{1 - \beta}$  (T. 10.11). Therefore, in view of Theorem 10.6, we have:

$$\frac{\gamma}{t_1} = \|c\|_{x_0}^* \leq \frac{1}{1 - r_0} \|c\|_{x_F^*}^* \leq \frac{1 - \beta}{1 - 2\beta} \|c\|_{x_F^*}^*.$$

Thus,  $t_k \geq \frac{\gamma(1 - 2\beta)}{(1 - \beta)\|c\|_{x_F^*}^*} \left(1 + \frac{\gamma}{\beta + \sqrt{\nu}}\right)^{k-1}$ ,  $k \geq 1$ . □

## Remarks:

1. The main term in the complexity estimate is

$$7.2\sqrt{\nu} \ln \frac{\nu \|c\|_{x_F^*}^*}{\epsilon}.$$

The value  $\nu \|c\|_{x_F^*}^*$  estimates the variation of  $\langle c, x \rangle$  on  $\text{Dom } F$  (see Theorem 7.6). Thus,

$$\frac{\epsilon}{\nu \|c\|_{x_F^*}^*}$$

is a *relative accuracy* of the solution.

2. It is not too often, when the starting condition

$$\|F'(x_0)\|_{x_0}^* \leq \beta$$

can be easily satisfied.

Therefore we need an additional process for *finding* such starting point.

Namely, we need a process for finding an approximation to the *analytic center* of the set  $\text{Dom } F$ .

## Finding the analytic center

### Problem:

$$\min\{F(x) \mid x \in \text{dom } F\}, \quad (7.21)$$

where  $F$  is a  $\nu$ -self-concordant barrier.

### Approximate solution:

Find  $\bar{x} \in \text{dom } F$  such that

$$\|F'(\bar{x})\|_{\bar{x}}^* \leq \beta,$$

where  $\beta \in (0, 1)$ .

There are two possibilities:

1. Damped Newton Method.
2. Path-following scheme.



## Damped Newton Method

0. Choose  $y_0 \in \text{dom } F$ .
1.  $k$ th iteration ( $k \geq 0$ ).

Set

$$y_{k+1} = y_k - \frac{[F''(y_k)]^{-1} F'(y_k)}{1 + \|F'(y_k)\|_{y_k}^*}. \quad (7.22)$$

2. Stop the process if  $\|F'(y_k)\|_{y_k}^* \leq \beta$ . □

**Theorem 7.10** *The process (7.22) terminates no more than after*

$$\frac{1}{\omega(\beta)}(F(y_0) - F(x_F^*))$$

*iterations.*

**Proof:**

Indeed, in view of Theorem 6.10, we have:

$$F(y_{k+1}) \leq F(y_k) - \omega(\lambda_F(y_k)) \leq F(y_k) - \omega(\beta).$$

Therefore

$$F(y_0) - k\omega(\beta) \geq F(y_k) \geq F(x_F^*).$$

□

## Auxiliary path-following scheme

Let us choose  $y_0 \in \text{dom } F$ .

Define the *auxiliary* central path:

$$y^*(t) = \arg \min_{y \in \text{dom } F} [-t \langle F'(y_0), y \rangle + F(y)],$$

where  $t \geq 0$ .

This trajectory is a solution of the equation:

$$F'(y^*(t)) = tF'(y_0). \quad (7.23)$$

Therefore

$$\begin{aligned} y^*(1) &= y_0, \\ y^*(0) &= x_F^*. \end{aligned}$$

### Note:

We can follow this trajectory by the process (7.16) with *decreasing*  $t$ .

Let us describe the convergence of  $y^*(t)$  to the analytic center.

**Lemma 7.2** *For any  $t \geq 0$  we have:*

$$\| F'(y^*(t)) \|_{y^*(t)}^* \leq (\nu + 2\sqrt{\nu}) \| F'(x_0) \|_{x_F^*}^* \cdot t.$$

### Proof:

This estimate follows from the equation (7.23) and Corollary 7.1. □

## Auxiliary Process (7.24)

0. Choose  $y_0 \in \text{Dom } F$ . Set  $t_0 = 1$ .

1.  $k$ th iteration ( $k \geq 0$ ).

Set

$$t_{k+1} = t_k - \frac{\gamma}{\|F'(y_0)\|_{y_k}^*},$$

$$y_{k+1} = y_k - [F''(y_k)]^{-1}(t_{k+1}F'(y_0) + F'(y_k)).$$

2. Stop the process if  $\|F'(y_k)\|_{y_k} \leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}}$ .

$$\text{Set } \bar{x} = y_k - [F''(y_k)]^{-1}F'(y_k). \quad \square$$

### Comments:

1. This scheme follows the trajectory  $y^*(t)$ :

$$\|t_k F'(y_0) + F'(y_k)\|_{y_k} \leq \beta,$$

as  $t_k \rightarrow 0$ .

2. The termination criterion,

$$\lambda_k = \|F'(y_k)\|_{y_k} \leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}},$$

guarantees that

$$\|F'(\bar{x})\|_{\bar{x}} \leq \left(\frac{\lambda_k}{1-\lambda_k}\right)^2 \leq \beta$$

(see Theorem 6.12).

**Theorem 7.11** *The process (7.24) terminates at most after*

$$\frac{1}{\gamma}(\beta + \sqrt{\nu}) \ln \left[ \frac{1}{\gamma}(\nu + 2\sqrt{\nu}) \| F'(x_0) \|_{x_F^*}^* \right]$$

*iterations.*

**Proof:**

Recall that we have fixed the parameters:

$$\beta = \frac{1}{9}, \quad \gamma = \frac{\sqrt{\beta}}{1+\sqrt{\beta}} - \beta = \frac{5}{36}.$$

Note that  $t_0 = 1$ . Therefore, in view of Theorem 7.8 and Lemma 7.1, we have:

$$t_{k+1} \leq \left( 1 - \frac{\gamma}{\beta + \sqrt{\nu}} \right) t_k \leq \exp \left( -\frac{\gamma(k+1)}{\beta + \sqrt{\nu}} \right).$$

Further, in view of Lemma 7.2, we obtain:

$$\begin{aligned} \| F'(y_k) \|_{y_k}^* &= \| (t_k F'(x_0) + F'(y_k)) - t_k F'(x_0) \|_{y_k}^* \\ &\leq \beta + t_k \| F'(x_0) \|_{y_k}^* \\ &\leq \beta + t_k(\nu + 2\sqrt{\nu}) \| F'(x_0) \|_{x_F^*}^* . \end{aligned}$$

Thus, the process is terminated at most when the following inequality holds:

$$t_k(\nu + 2\sqrt{\nu}) \| F'(x_0) \|_{x_F^*}^* \leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}} - \beta = \gamma.$$

□

## Remarks:

1. The principal term in the complexity is

$$7.2\sqrt{\nu}[\ln \nu + \ln \| F'(x_0) \|_{x_F^*}^*]$$

for the auxiliary path-following scheme and

$$O(F(y_0) - F(x_F^*))$$

for the auxiliary Damped Newton Method.

Now we cannot compare these estimates.

However, a more sophisticated analysis demonstrates the advantages of path-following scheme.

2. The principal term in the total complexity of the path-following scheme (7.20) with the auxiliary process (7.24) is

$$7.2\sqrt{\nu} \left[ 2 \ln \nu + \ln \| F'(x_0) \|_{x_F^*}^* + \ln \| c \|_{x_F^*}^* + \ln \frac{1}{\epsilon} \right].$$

3. For some problems it is difficult to find a starting point  $y_0 \in \text{dom } F$ .

To do that, we can introduce one more auxiliary process.

## Problems with functional constraints

**Problem:**

$$\begin{aligned} & \min f_0(x), \\ & \text{s.t. } f_j(x) \leq 0, \quad j = 1 \dots m, \\ & \quad x \in Q, \end{aligned} \tag{7.25}$$

where

- $Q$  is a bounded closed convex set,  $\text{int } Q \neq \emptyset$ .
- $f_j, j = 0 \dots m$ , are convex.

**Assumptions:**

- $\exists \bar{x} \in \text{int } Q: f_j(\bar{x}) < 0, j = 1 \dots m$ .
- We know  $\bar{\tau}: f_0(x) < \bar{\tau}$  for all  $x \in Q$ .

**Equivalent standard problem:**

$$\begin{aligned} & \min \tau, \\ & \text{s.t. } f_0(x) \leq \tau, \\ & \quad f_j(x) \leq \kappa, \quad j = 1 \dots m, \\ & \quad x \in Q, \quad \tau \leq \bar{\tau}, \quad \kappa \leq 0. \end{aligned} \tag{7.26}$$

We need the following self-concordant barriers:

- $F_Q(x)$  for the set  $Q$ .
- $F_0(x, \tau)$  for the epigraph of  $f_0(x)$ .
- $F_j(x, \kappa)$  for the epigraphs of  $f_j(x)$ ,  $j = 1 \dots m$ .

Assume that we can do that. Then we can use

$$\begin{aligned} \hat{F}(x, \tau, \kappa) &= F_Q(x) + F_0(x, \tau) + \sum_{j=1}^m F_j(x, \kappa) \\ &\quad - \ln(\bar{\tau} - \tau) - \ln(-\kappa). \\ \hat{\nu} &= \nu_Q + \nu_0 + \sum_{j=1}^m \nu_j + 2. \end{aligned} \tag{7.27}$$

**Note:**

- It could be difficult to find a point from  $\text{dom } \hat{F}$ .
- If  $x_0 \in \text{int } Q$ , then for large  $\tau_0$  and  $\kappa_0$  we have:

$$f_0(x_0) < \tau_0 < \bar{\tau}, \quad f_j(x_0) < \kappa_0, \quad j = 1 \dots m.$$

But  $\kappa \leq 0$  could be violated.

**New notation:**

$$\begin{aligned} & \min \langle c, z \rangle, \\ \text{s.t. } & z \in S, \\ & \langle d, z \rangle \leq 0, \end{aligned} \tag{7.28}$$

where

- $z = (x, \tau, \kappa)$ ,
- $\langle c, z \rangle \equiv \tau$ ,
- $\langle d, z \rangle \equiv \kappa$ ,
- $S$  is the feasible set (7.26) without the constraint  $\kappa \leq 0$ .

**We know:**

- A self-concordant barrier  $F(z)$  for  $S$ .
- A point  $z_0 \in \text{int } S$ .
- The set  $S(\alpha) = \{z \in S \mid \langle d, z \rangle \leq \alpha\}$  is bounded.
- For  $\alpha$  large enough  $\text{int } S(\alpha) \neq \emptyset$ .

We solve (7.28) in *three* stages.



## First Stage:

1. Choose a starting point  $z_0 \in \text{int } S$ .
2. Choose an initial gap  $\Delta > 0$ .

Set  $\alpha = \langle d, z_0 \rangle + \Delta$ .

If  $\alpha \leq 0$ , apply the two-stage scheme.

3. Otherwise, find an approximate analytic center of  $S(\alpha)$ , using

$$\tilde{F}(z) = F(z) - \ln(\alpha - \langle d, z \rangle).$$

We find a point  $\tilde{z}$  satisfying the condition

$$\begin{aligned} & \langle \tilde{F}''(\tilde{z})^{-1} \left( F'(\tilde{z}) + \frac{d}{\alpha - \langle d, \tilde{z} \rangle} \right), F'(\tilde{z}) + \frac{d}{\alpha - \langle d, \tilde{z} \rangle} \rangle^{1/2} \\ & \equiv \lambda_{\tilde{F}}(\tilde{z}) \leq \beta. \end{aligned}$$

To do that, we can apply the auxiliary path-following schemes.

## Second Stage:

Follow the central path  $z(t)$ :

$$td + \tilde{F}'(z(t)) = 0, \quad t \geq 0.$$

### Note:

- The first stage computes an approximation to  $z(0)$ , the analytic center  $S(\alpha)$ .
- We can follow this path, using (7.16).
- This trajectory leads us to the solution of

$$\min\{\langle d, z \rangle \mid z \in S(\alpha)\} \quad (< 0)$$

(Slater condition for problem (7.28)).

### Goal:

Find an approximation to the analytic center of

$$\bar{S} = \{z \in S(\alpha) \mid \langle d, z \rangle \leq 0\},$$

generated by the barrier  $\bar{F}(z) = \tilde{F}(z) - \ln(-\langle d, z \rangle)$ .

For this point,  $z_*$ , we have:

$$\tilde{F}'(z_*) - \frac{d}{\langle d, z_* \rangle} = 0.$$

Therefore  $\exists t_* : z_* = z(t_*)$ . Namely,  $t_* = -\frac{1}{\langle d, z_* \rangle} > 0$ .

This stage computes  $\bar{z}$ :

$$\begin{aligned} & \langle \tilde{F}''(\bar{z})^{-1} \left( \tilde{F}'(\bar{z}) - \frac{d}{\langle d, \bar{z} \rangle} \right), \tilde{F}'(\bar{z}) - \frac{d}{\langle d, \bar{z} \rangle} \rangle^{1/2} \\ & \equiv \lambda_{\tilde{F}}(\bar{z}) \leq \beta. \end{aligned}$$

### Third Stage:

Since  $\bar{F}''(z) > \tilde{F}''(z)$ , we have:

$$\begin{aligned} & \langle \bar{F}''(\tilde{z})^{-1} \left( \tilde{F}'(\bar{z}) - \frac{d}{\langle d, \bar{z} \rangle} \right), \tilde{F}'(\bar{z}) - \frac{d}{\langle d, \bar{z} \rangle} \rangle^{1/2} \\ & \equiv \lambda_{\bar{F}}(\bar{z}) \leq \beta. \end{aligned}$$

Therefore:

- $\bar{z}$  is a good approximation to the analytic center of the set  $\bar{S}$ .
- We can apply the main path-following scheme (7.20) to solve the problem

$$\min \{ \langle c, z \rangle \mid z \in \bar{S} \}.$$

This problem is equivalent to (7.28).

### Remarks:

1. We omit the detailed complexity analysis.
2. The main term in the complexity of this scheme

$$\sqrt{\hat{\nu}} \cdot \left( \ln \frac{1}{\epsilon} + \dots \right),$$

(see (7.27)), where “...” are the logarithms of some structural characteristics of the problem (size of the region, deepness of the Slater condition, etc.).

**Note:** We need to know how to construct the self-concordant barriers, hopefully with *small* value of the parameter.